IN THE CLAIMS:

The text of all pending claims, (including withdrawn claims) is set forth below. Cancelled and not entered claims are indicated with claim number and status only. The claims as listed below show added text with underlining and deleted text with ~~strikethrough~~. The status of each claim is indicated with one of (original), (currently amended), (cancelled), (withdrawn), (new), (previously presented), or (not entered).

Please AMEND claims 1, 7, and 12 and ADD new claim 19 in accordance with the following:

1. (CURRENTLY AMENDED) A method of selling a commodity via a network, said method comprising:

if instruction information regarding moving ~~an~~ a selected article~~, which was selected from among a plurality of articles of one commodity,~~ in at least one of a variety of positions for display and operating a camera included in a robot according to said moving is received from a user terminal, outputting to said robot, a first request for acquiring image information at this moment according to said moving of the selected article itself, said robot provided for a real shop and moving around within said real shop; and

transmitting to said user terminal, said image information of the selected article itself to enable a user of said user terminal to evaluate an actual state of the selected article itself, said image information taken by said camera included in said robot.

2. (PREVIOUSLY PRESENTED) The method as set forth in claim 1, further comprising:

if information regarding a selected purchase plan commodity is received from said user terminal, outputting to said robot, a second request for acquiring image information for said selected purchase plan commodity;

according to said second request, controlling said robot to move while taking image information until said robot reaches an exhibition position of said selected purchase plan commodity; and

transmitting to said user terminal, image information for said selected purchase plan commodity, which is taken by said camera included in said robot, and image information until said robot reaches said exhibition position of said selected purchase plan commodity, to enable said user of said user terminal to see an actual state within said real shop in real time.

3. (PREVIOUSLY PRESENTED) The method as set forth in claim 1, further comprising:

according to said first request, controlling said robot to change a photographing method for the selected article itself; and

if a purchase instruction of the selected article is received from said user terminal, instructing said robot to convey said selected article within said real shop.

4. (CANCELLED)

5. (PREVIOUSLY PRESENTED) The method as set forth in claim 1, further comprising:

if a purchase instruction of the selected article is received from said user terminal, acquiring identification information of said selected article itself; and

transmitting said identification information of said selected article itself to said user terminal.

6. (CANCELLED)

7. (CURRENTLY AMENDED) A computer program embodied on a medium, for causing a computer to sell a commodity via a network, said program comprising:

if instruction information regarding moving ~~an~~ a selected article~~, which was selected from among a plurality of articles of one commodity,~~ in at least one of a variety of positions for display and operating a camera included in a robot according to said moving, ~~which was selected among a plurality of articles of one commodity,~~ is received from a user terminal, outputting to said robot, a first request for acquiring image information at this moment according to said moving of the selected article itself, said robot provided for a real shop and moving around within said real shop; and

transmitting to said user terminal, said image information of the selected article itself to enable a user of said user terminal to evaluate an actual state of the selected article itself, said image information taken by said camera included in said robot.

8. (PREVIOUSLY PRESENTED) The computer program as set forth in claim 7, further comprising:

if information regarding a selected purchase plan commodity is received from said user terminal, outputting to said robot, a second request for acquiring image information for said selected purchase plan commodity;

according to said second request, controlling said robot to move while taking image information until said robot reaches an exhibition position of said selected purchase plan commodity; and

transmitting to said user terminal, image information for said selected purchase plan commodity, which is taken by said camera included in said robot, and image information until said robot reaches said exhibition position of said selected purchase plan commodity, to enable said user of said user terminal to see an actual state within said real shop in real time.

9. (PREVIOUSLY PRESENTED) The computer program as set forth in claim 7, further comprising:

according to said first request, controlling said robot to change a photographing method for the selected article itself; and

if a purchase instruction of the selected article is received from said user terminal, instructing said robot to convey said selected article within said real shop.

10. (CANCELLED)

11. (PREVIOUSLY PRESENTED) The computer program as set forth in claim 7, further comprising:

if a purchase instruction of the selected article is received from said user terminal, acquiring identification information of said selected article itself; and

transmitting said identification information of said selected article itself to said user terminal.

12. (CURRENTLY AMENDED) A computer system for selling a commodity via a network, comprising:

a receiver receiving ~~an~~ instruction information regarding moving ~~an~~ a selected article, ~~which was selected among a plurality of articles of one commodity~~ from a user terminal in at least one of a variety of positions for display and operating a camera included in a robot according to said moving;

an outputting unit that outputs to said robot, a first request for acquiring image

information at this moment according to said moving of said selected article itself, said robot provided for a real shop and moving around within said real shop; and

a transmitter transmitting to said user terminal, said image information of the selected article itself to enable a user of said user terminal to evaluate an actual state of the selected article itself, said image information taken by said camera included in said robot.

13. (PREVIOUSLY PRESENTED) The computer system as set forth in claim 12, further comprising:

a second receiver receiving information regarding a selected purchase plan commodity from said user terminal;

a second outputting unit that outputs to said robot, a second request for acquiring image information for said selected purchase plan commodity in the received information;

a controller controlling said robot to move while taking image information until said robot reaches an exhibition position of said selected purchase plan commodity, according to said second request; and

a second transmitter transmitting to said user terminal, image information for said selected purchase plan commodity, which is taken by said camera included in said robot, and image information until said robot reaches said exhibition position of said selected purchase plan commodity, to enable said user of said user terminal to see an actual state within said real shop in real time.

14. (PREVIOUSLY PRESENTED) The computer system as set forth in claim 12, further comprising:

a second controller controlling said robot to change a photographing method for the selected article itself, according to said first photographing request;

a third receiver receiving a purchase instruction of the selected article from said user terminal; and

a third controller instructing said robot to convey said selected article within said real shop in response to said purchase instruction.

15. (CANCELLED)

16. (PREVIOUSLY PRESENTED) The computer system as set forth in claim 12, further comprising:

a fourth receiver for receiving a purchase instruction of the selected article from said user terminal;

an acquiring unit that acquires identification information of said selected article itself in response to said purchase instruction; and

a third transmitter transmitting said identification information of said selected article itself to said user terminal.

17. (PREVIOUSLY PRESENTED) The method as set forth in claim 1, further comprising:

if third instruction information regarding a selection of another article of said one commodity is received from said user terminal, outputting to said robot, a third request for acquiring image information for said another article at this moment according to said third instruction information; and

transmitting to said user terminal, said image information for said another article to enable said user of said user terminal to evaluate an actual state of said another article itself, said image information taken by said camera included in said robot.

18. (PREVIOUSLY PRESENTED) The method as set forth in claim 1, further comprising:

if a voice request is received, outputting to said robot including a microphone, an instruction to obtain voice information within said real shop; and

transmitting to said user terminal, the obtained voice information to enable said user of said user terminal to represent an actual state within said real shop in real time.

19. (NEW) A method of selling an item, comprising:

receiving instruction information at a robot including information pertaining to manipulating a selected object to place the object in at least one of a variety of directional orientations, said instruction information including information pertaining to obtaining an image according to said manipulating; and

receiving a purchase instruction based on an evaluation resulting from inspection of said object as said object appears in said image.